

MLFB-Ordering data

6SL3210-1KE32-4UF1



Client order no. : Order no. : Offer no. :

Remarks:

Item no. : Consignment no. : Project :

Rated data			
Input			
Number of phases	3 AC		
Line voltage	380 480 V +10 % -20 %		
Line frequency	47 63 Hz		
Rated current (LO)	221.00 A		
Rated current (HO)	207.00 A		
Output			
Number of phases	3 AC		
Rated voltage	400 V		
Rated power IEC 400V (LO)	132.00 kW		
Rated power NEC 480V (LO)	150.00 hp		
Rated power IEC 400V (HO)	110.00 kW		
Rated power NEC 480V (HO)	125.00 hp		
Rated current (LO)	237.00 A		
Rated current (HO)	201.00 A		
Rated current (IN)	237.00 A		
Max. output current	402.00 A		
Pulse frequency	2 kHz		
Output frequency for vector control	0 240 Hz		
Output frequency for V/f control	0 550 Hz		

Overload capability

Low Overload (LO)

 $150\ \%$ base load current IL for 3 s, followed by $110\ \%$ base load current IL for 57 s in a $300\ s$ cycle time

High Overload (HO)

 $200\,\%$ base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
D (c. t)	0.00	
Power factor λ	0.90 0.95	
Offset factor cos φ	0.99	
Efficiency η	0.99	
Sound pressure level (1m)	68 dB	
Power loss	2.33 kW	
Filter class (integrated)	Unfiltered	

Ambient conditions		
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.153 m³/s (5.403 ft³/s)	
Installation altitude	1000 m (3280.84 ft)	
Ambient temperature		
Operation	-20 40 °C (-4 104 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-40 70 °C (-40 158 °F)	
Relative humidity		

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	

Max. operation

95 % RH, condensation not permitted



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			Figure :
Mechanical	data	Com	nmunication
Degree of protection	IP20 / UL open type	Communication	PROFINET, EtherNet/IP
Size	FSF	Co	nnections
Net weight	61.50 kg (135.58 lb)	Signal cable	
Width	305 mm (12.01 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 10
Height	708 mm (27.87 in)	Line side	
Depth	357 mm (14.06 in)	Version	screw-type terminal
Inputs / out	tputs	Conductor cross-section	35.00 120.00 mm² (AWG 2 AWG
tandard digital inputs		Motor end	
Number	6	Version	Screw-type terminals
Switching level: 0→1	11 V	Conductor cross-section	35.00 120.00 mm² (AWG 2 AWG
Switching level: 1→0	5 V	DC link (for braking resistor)
Max. inrush current	15 mA	Version	Screw-type terminals
ail-safe digital inputs		Conductor cross-section	35.00 120.00 mm² (AWG 2 AWG
Number	1	Line length, max.	10 m (32.81 ft)
igital outputs		PE connection	Screw-type terminals
Number as relay changeover contact	1	Max. motor cable length	3 [
Output (resistive load)	DC 30 V, 0.5 A	Shielded	300 m (984.25 ft)
Number as transistor	1	Unshielded	450 m (1476.38 ft)
Output (resistive load)	DC 30 V, 0.5 A	Standards	
nalog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)
Number	1 (Differential input)		,,,,,,
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Volt Directive 2006/95/EC
witching threshold as digital in	put		
0→1	4 V		
1→0	1.6 V		
nalog outputs			

PTC/ KTY interface

Number

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$

1 (Non-isolated output)



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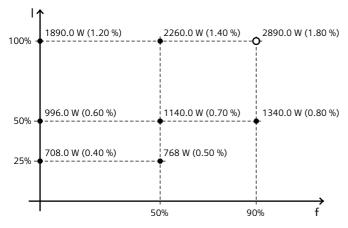
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Figure similar

Converter losses to IEC61800-9-2*

Efficiency class	IE2
Comparison with the reference converter (90% /	43.10 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values